## CS221 Problem Workout Solutions

## Week 1

Welcome to CS 221! During the problem sessions, we will work through practice homework and exam problems. If you have any questions, comments, concerns, feel free to reach out to the problem session lead Samantha Liu, and co-presenter Neil Nie. Here are some key takeaways from this week:

## Key Takeaways from this Week

1. Syllabus: Please take some time and review the course syllabus. If you have any questions or concerns, please reach out to the instructors and or CAs.

## 2. Gradient and Gradient Descent:

- Gradient: the vector representing the direction and rate of the fastest increase of a scalar-valued function $f$ at a point. $\nabla f$ can be derived by taking all partial derivatives of $f$ and forming them into a vector-valued function.
- Gradient Descent: an optimization algorithm for finding the local minimum of a differential function $f$ by taking repeated steps in the opposite direction of the gradient at the current point.

3. Loss Functions (Preview): The measure of how far the model's prediction is from the real (or ground truth) $y$.

## 1 Practice Problems

## 1) Problem 1: Gradient computation

(i) Let $\phi(x): \mathbb{R} \mapsto \mathbb{R}^{d}$ and $\mathbf{w} \in \mathbb{R}^{d}$. Consider the following loss function.

$$
\begin{equation*}
\operatorname{Loss}(x, y, \mathbf{w})=\frac{1}{2} \max \{2-(\mathbf{w} \cdot \phi(x)) y, 0\}^{2} \tag{1}
\end{equation*}
$$

Compute its gradient $\nabla_{\mathbf{w}} \operatorname{Loss}(x, y, \mathbf{w})$.

Solution Note that $\operatorname{Loss}(x, y, w)$ can be written as the following piecewise-defined function using the definition of max.

$$
\operatorname{Loss}(x, y, \mathbf{w})= \begin{cases}\frac{1}{2}(2-(\mathbf{w} \cdot \phi(x) y))^{2} & \text { if } 2-(\mathbf{w} \cdot \phi(x)) y \geq 0  \tag{2}\\ 0 & \text { otherwise }\end{cases}
$$

Using the chain rule, we get that the gradient is:

$$
\nabla_{\mathbf{w}} \operatorname{Loss}(x, y, \mathbf{w})= \begin{cases}-(2-\mathbf{w} \cdot \phi(x) y) \phi(x) y & \text { if } 2-\mathbf{w} \cdot \phi(x) y \geq 0  \tag{3}\\ 0 & \text { otherwise }\end{cases}
$$

## 2) Problem 2: More gradient computations

(i) Compute the gradient of the loss function below.

$$
\begin{equation*}
\operatorname{Loss}(x, y, \mathbf{w})=\sigma(-(\mathbf{w} \cdot \phi(x)) y) \tag{4}
\end{equation*}
$$

where $\sigma(z)=(1+\exp (-z))^{-1}$ is the logistic function.

Solution Let $z=(-\mathbf{w} \cdot \phi(x)) y$, then $\operatorname{Loss}(x, y, \mathbf{w})=\sigma(z)=(1+\exp (-z))^{-1}$. Applying the chain rule, we get

$$
\begin{align*}
\nabla_{\mathbf{w}} \operatorname{Loss}(x, y, \mathbf{w}) & =\frac{\partial \sigma(z)}{\partial z} \nabla_{\mathbf{w}} z  \tag{5}\\
& =-(1+\exp (-z))^{-2} \exp (-z) y \phi(x)  \tag{6}\\
& =-(1+\exp (-z))^{-1}\left(\frac{\exp (-z)}{1+\exp (-z)}\right) y \phi(x)  \tag{7}\\
& =-\sigma(z)(1-\sigma(z)) y \phi(x) . \tag{8}
\end{align*}
$$

Plugging in the expression for $z$ gives us the final expression.

$$
\begin{equation*}
\nabla_{\mathbf{w}} \operatorname{Loss}(x, y, \mathbf{w})=-\sigma(-(\mathbf{w} \cdot \phi(x)) y)(1-\sigma(-(\mathbf{w} \cdot \phi(x)) y)) y \phi(x) \tag{9}
\end{equation*}
$$

(ii) Suppose we have the following loss function.

$$
\begin{equation*}
\operatorname{Loss}(x, y, \mathbf{w})=\max \{1-\lfloor(\mathbf{w} \cdot \phi(x)) y\rfloor, 0\} \tag{10}
\end{equation*}
$$

where $\lfloor a\rfloor$ returns $a$ rounded down to the nearest integer. Determine what the gradient of this function looks like, and whether gradient descent is suitable to optimize this loss function.

## Solution

$$
\operatorname{Loss}(x, y, \mathbf{w})= \begin{cases}1-\lfloor(\mathbf{w} \cdot \phi(x)) y\rfloor & \text { if }\lfloor(\mathbf{w} \cdot \phi(x)) y\rfloor \leq 1  \tag{11}\\ 0 & \text { otherwise }\end{cases}
$$

If we draw the plot for the floor function (see below), we can see that its derivative is 0 (the lines are flat and the slope is 0 ) almost everywhere.


Thus, when applying chain rule to find the gradient of $\operatorname{Loss}(x, y, \mathbf{w})$, the computed gradient will also be 0 almost everywhere, so gradient descent is not suitable to optimize this function as the iterates would not move from the point of initialization.

## 3) Problem 3: Gradient and Gradient Descent

(i) Let $\phi(x): \mathbb{R} \mapsto \mathbb{R}^{d}, \mathbf{w} \in \mathbb{R}^{d}$. Consider the following loss function.

$$
\operatorname{Loss}(x, y, \mathbf{w})= \begin{cases}1-2(\mathbf{w} \cdot \phi(x)) y & \text { if }(\mathbf{w} \cdot \phi(x)) y \leq 0 \\ (1-(\mathbf{w} \cdot \phi(x)) y)^{2} & \text { if } 0<(\mathbf{w} \cdot \phi(x)) y \leq 1 \\ 0 & \text { if }(\mathbf{w} \cdot \phi(x)) y>1\end{cases}
$$

where $y \in \mathbb{R}$. Compute the gradient $\nabla_{\mathbf{w}} \operatorname{Loss}(x, y, \mathbf{w})$.

Solution We apply the rules to compute the gradient for each case separately, leading to the following piece-wise function for the gradient.

$$
\nabla_{\mathbf{w}} \operatorname{Loss}(x, y, \mathbf{w})= \begin{cases}-2 \phi(x) y & \text { if }(\mathbf{w} \cdot \phi(x)) y \leq 0  \tag{12}\\ -2(1-(\mathbf{w} \cdot \phi(x)) y) \phi(x) y & \text { if } 0<(\mathbf{w} \cdot \phi(x)) y \leq 1 \\ 0 & \text { if }(\mathbf{w} \cdot \phi(x)) y>1\end{cases}
$$

(ii) Let $d=2$ and $\phi(x)=[1, x]$. Consider the following training loss function.

$$
\begin{equation*}
\operatorname{TrainLoss}(\mathbf{w})=\frac{1}{2}\left(\operatorname{Loss}\left(x_{1}, y_{1}, \mathbf{w}\right)+\operatorname{Loss}\left(x_{2}, y_{2}, \mathbf{w}\right)\right) \tag{13}
\end{equation*}
$$

Compute $\nabla_{w} \operatorname{TrainLoss}(\mathbf{w})$ for the following values of $x_{1}, y_{1}, x_{2}, y_{2}, \mathbf{w}$.

$$
\begin{gathered}
\mathbf{w}=\left[0, \frac{1}{2}\right], \\
x_{1}=-2, \quad y_{1}=1, \\
x_{2}=-1, \quad y_{2}=-1 .
\end{gathered}
$$

## Solution

$$
\begin{aligned}
\nabla_{w} \operatorname{TrainLoss}(\mathbf{w}) & =\frac{1}{2} \nabla_{\mathbf{w}}\left(\operatorname{Loss}\left(x_{1}, y_{1}, \mathbf{w}\right)+\operatorname{Loss}\left(x_{2}, y_{2}, \mathbf{w}\right)\right) \\
& =\frac{1}{2} \nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{1}, y_{1}, \mathbf{w}\right)+\frac{1}{2} \nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{2}, y_{2}, \mathbf{w}\right)
\end{aligned}
$$

For each of the terms above, we plug in the expression for the gradient computed in part (i) above.

Term one. Note that $\phi\left(x_{1}\right)=[1,-2]$. Since $\left(\mathbf{w} \cdot \phi\left(x_{1}\right)\right) y_{1}=-1$, we consider the first piece (Case 1) in the gradient expression (Equation 12). We have

$$
\begin{align*}
\nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{1}, y_{1}, \mathbf{w}\right) & =-2 \phi\left(x_{1}\right) y_{1} \\
& =[-2,4] . \tag{14}
\end{align*}
$$

Term two. Note that $\phi\left(x_{2}\right)=[1,-1]$. Similarly, $\left(\mathbf{w} \cdot \phi\left(x_{2}\right)\right) y_{2}=\frac{1}{2}$ taking us to Case 2 so

$$
\begin{align*}
\nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{2}, y_{2}, \mathbf{w}\right) & =-2\left(1-\left(\mathbf{w} \cdot \phi\left(x_{2}\right)\right) y_{2}\right) \phi\left(x_{2}\right) y_{2} \\
& =[1,-1] . \tag{15}
\end{align*}
$$

Combining the terms,

$$
\begin{align*}
\nabla_{\mathbf{w}} \operatorname{TrainLoss}(\mathbf{w}) & =\frac{1}{2}([-2,4]+[1,-1]) \\
& =\left[-\frac{1}{2}, \frac{3}{2}\right] \tag{16}
\end{align*}
$$

(iii) Now, let's define the Gradient Descent update rule for some function TrainLoss(w) : $\mathbb{R}^{d} \mapsto \mathbb{R}$. The rule helps us update the weights w.

$$
\begin{equation*}
\mathbf{w}:=\mathbf{w}-\eta \nabla_{\mathbf{w}} \operatorname{TrainLoss}(\mathbf{w}), \text { where } \eta \text { is the step size. } \tag{17}
\end{equation*}
$$

Perform two iterations of Gradient Descent to minimize the objective function $\operatorname{TrainLoss}(\mathbf{w})=\frac{1}{2}\left(\operatorname{Loss}\left(x_{1}, y_{1}, w\right)+\operatorname{Loss}\left(x_{2}, y_{2}, w\right)\right)$ with values for $x_{1}, y_{1}, x_{2}, y_{2}$ from part (iii), using the weights update equation above. Use initialization $\mathbf{w}^{0}=\left[0, \frac{1}{2}\right]$ and step size $\eta=\frac{1}{2}$.

Solution Note that we have already computed $\nabla_{\mathbf{w}} \operatorname{TrainLoss}(\mathbf{w})$ at the initialization point $\mathbf{w}^{0}$ in the question above.

$$
\begin{aligned}
\mathbf{w}^{1} & =\mathbf{w}^{0}-\eta \nabla_{\mathbf{w}} \operatorname{TrainLoss}(\mathbf{w}) \text { at } \mathbf{w}^{0} \\
& =\left[0, \frac{1}{2}\right]-\left(\frac{1}{2}\right) \underbrace{\left(\frac{1}{2}\right)[-1,3]}_{\text {From part (iii) above }} \\
& =\left[\frac{1}{4},-\frac{1}{4}\right] .
\end{aligned}
$$

Now we need to compute $\nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{1}, y_{1}, \mathbf{w}\right)$ and $\nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{2}, y_{2}, \mathbf{w}\right)$ at the new iterate $\mathrm{w}^{1}$.
We repeat the process we did for (iii) by applying the piece-wise defined gradient (Equation 12 to the two points, this time setting $\mathbf{w}=\mathbf{w}^{1}$.

Term one. Since $\left(\mathbf{w}^{1} \cdot \phi\left(x_{1}\right)\right) y_{1}=\frac{3}{4}$, we have $\nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{1}, y_{1}, \mathbf{w}\right)=-2\left(1-\left(\mathbf{w}^{1}\right.\right.$. $\left.\left.\phi\left(x_{1}\right)\right) y_{1}\right) \phi\left(x_{1}\right) y_{1}=\left[-\frac{1}{2}, 1\right]$. Note that we are now in Case 2 with respect to the piecewise definition of the gradient (Equation 12 . When computing $\nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{1}, y_{1}, \mathbf{w}\right)$ at $w^{0}$, we were in Case 1.

Term two. $\left(\mathbf{w}^{1} \cdot \phi\left(x_{2}\right)\right) y_{2}=-\frac{1}{2}$ taking us to Case 1, so $\nabla_{\mathbf{w}} \operatorname{Loss}\left(x_{2}, y_{2}, \mathbf{w}\right)=$ $-2 \phi\left(x_{2}\right) y_{2}=[2,-2]$.

Hence,

$$
\begin{aligned}
\mathbf{w}^{2} & =\mathbf{w}^{1}-\eta \nabla_{\mathbf{w}} \operatorname{TrainLoss}(\mathbf{w}) \text { at } \mathbf{w}^{1} \\
& =\left[\frac{1}{4},-\frac{1}{4}\right]-\left(\frac{1}{2}\right)\left(\frac{1}{2}\right)\left(\left[-\frac{1}{2}, 1\right]+[2,-2]\right) \\
& =\left[-\frac{1}{8}, 0\right] .
\end{aligned}
$$

## 4) Problem 4 (Extra): Vector visualization

Recall that we can visualize a vector $\mathbf{w} \in \mathbb{R}^{d}$ as a point in d-dimensional space. Let us now visualize some vectors in 2 dimensions on pen and paper.
(i) Consider $\mathbf{x} \in \mathbb{R}^{2}$. Draw the line (i.e. the "decision boundary") that separates between vectors having a positive dot product with weights $\mathbf{w}=[3,-2]$ and those having a negative dot product. Shade the part of the 2D plane that contains vectors satisfying $\mathbf{w} \cdot \mathbf{x}>0$.
Hint: It might help to write out the expression for the dot product and seeing the relation between $x_{1}$ and $x_{2}$ that leads to a positive dot product. You could also use the geometric interpretation of the dot product.

Solution $\quad \mathbf{w} \cdot \mathbf{x}=3 x_{1}-2 x_{2}>0$

(ii) Repeat the above for $\mathbf{w}=[2,0]$ and $\mathbf{w}=[0,2]$.

Solution When $\mathbf{w}=[2,0], \mathbf{w} \cdot \mathbf{x}=2 x_{1}>0$


When $\mathbf{w}=[0,2], \mathbf{w} \cdot \mathbf{x}=2 x_{2}>0$

(iii) A small twist: visualize the set of vectors where $\mathbf{w} \cdot \mathbf{x} \geq 1$ for $\mathbf{w}=[3,-2]$.

Solution $\quad \mathbf{w} \cdot \mathbf{x}=3 x_{1}-2 x_{2} \geq 1$, so $3 x_{1}-2 x_{2}-1 \geq 0$


Note that we get a line that is parallel to the one in (i) but shifted by a certain amount.
(iv) Consider the following element-wise inequality notation. For two vectors $\mathbf{a}, \mathbf{b} \in \mathbb{R}^{d}$,

$$
\begin{equation*}
\mathbf{a} \leq \mathbf{b} \Longleftrightarrow a_{i} \leq b_{i} \forall i=1,2, \ldots d \tag{18}
\end{equation*}
$$

Suppose we have a matrix $A \in \mathbb{R}^{2 \times 2}$ and a vector $\mathbf{b} \in \mathbb{R}^{2}$ as follows.

$$
A=\left[\begin{array}{cc}
3 & -2  \tag{19}\\
2 & 0
\end{array}\right], \mathbf{b}=[1,0] .
$$

Visualize the set of vectors where $A \mathbf{x} \geq \mathbf{b}$. Hint: A matrix vector product is a collection of dot products, and the above set can be obtained by the intersection of two of the sets constructed in the previous questions.

Solution $A \mathbf{x}=\left[3 x_{1}-2 x_{2}, 2 x_{1}\right] \geq[1,0]$, so it's the intersection of $3 x_{1}-2 x_{2} \geq 1$ and $x_{1} \geq 0$


